

# Chih-Yuan Chiu

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CONTACT INFORMATION	<i>E-mail:</i> <a href="mailto:chihyuan_chiu@berkeley.edu">chihyuan_chiu@berkeley.edu</a> <i>Website:</i> <a href="https://people.eecs.berkeley.edu/~chihyuan_chiu/">https://people.eecs.berkeley.edu/~chihyuan_chiu/</a> <i>Google Scholar:</i> <a href="https://scholar.google.com/citations?hl=en&amp;user=c19ModoAAAAJ">https://scholar.google.com/citations?hl=en&amp;user=c19ModoAAAAJ</a>
EDUCATION	<b>UC Berkeley</b> , Berkeley, CA <span style="float: right;">Sept 2018 - Present</span> <i>Ph.D. Student, Department of Electrical Engineering and Computer Sciences</i> <ul style="list-style-type: none"><li>• <b>Research Advisor:</b> Professor Shankar Sastry</li><li>• <b>Selected Coursework (Average GPA: 4.0):</b> Linear Systems Theory (A+), Information Theory (A), Random Processes in Systems (A+), Nonlinear Systems (A+), Machine Learning (A+), Metric Differential Geometry (A), Probability Theory (A+), Hybrid and Intelligent Systems Design (A+), Stochastic Systems (A), Convex Optimization (A), Optimization Analysis and Algorithms (A+), Theory of Multi-armed Bandits and Reinforcement Learning (A+), Introduction to Robotics (A)</li></ul> <b>National Taiwan University</b> , Taipei, Taiwan <span style="float: right;">Sept 2014 - June 2018</span> <i>B.S., Department of Electrical Engineering</i>
RESEARCH EXPERIENCE	<b>University of California, Berkeley</b> , Berkeley, CA 94720 <i>First-Year Graduate Student Fellowship</i> <span style="float: right;">Jul 2018 - Jun 2019</span> <i>Graduate Research Assistant</i> <span style="float: right;">Jul 2019 - Present</span> <ul style="list-style-type: none"><li>• Topics—Game Theory, State Estimation, Optimal Control, Computer Vision</li><li>• Advisor—Professor Shankar Sastry</li></ul>
TEACHING EXPERIENCE	<b>EE 16B (Designing Information Devices and Systems II)</b> , <span style="float: right;">Jul 2020 - Aug 2020</span> <i>25-hour Graduate Student Instructor for an 8-week summer course</i> <b>EE 221A (Linear Systems Theory)</b> , <span style="float: right;">Aug 2021 - Dec 2021</span> <i>20-hour Graduate Student Instructor for a 16-week semester-long course</i> <b>EE 127 (Optimization Models in Engineering)</b> , <span style="float: right;">Aug 2023 - Present</span> <i>20-hour Graduate Student Instructor for a 16-week semester-long course</i>
CONFERENCE REVIEWS	<b>Conferences and Journals</b> <ul style="list-style-type: none"><li>• Journal of Machine Learning Research (JMLR), 2023.</li><li>• IEEE Conference on Decision and Control (CDC), 2023.</li><li>• IEEE Robotics and Automation Letters (RA-L), 2023.</li><li>• IEEE American Control Conference (ACC), 2023.</li><li>• IEEE International Conference on Robotics and Automation (ICRA), 2022.</li><li>• International Symposium on Multi-Robot and Multi-Agent Systems (MRS), 2021.</li><li>• IEEE International Conference on Robotics and Automation (ICRA), 2021.</li><li>• IEEE Conference on Decision and Control (CDC), 2020.</li></ul>
ACADEMIC TRANSLATION LANGUAGES	Yung, Chee Fai, <i>Linear Algebra</i> , 2nd ed., 2012, Wuhan Book Co., Ltd., Taiwan (to be published). <b>Mandarin Chinese</b> , Native language <b>English</b> , Fluent

SOFTWARE SKILL	Python, Matlab, C++, L <sup>A</sup> T <sub>E</sub> X, ROS
ORGANIZATIONS AND ACTIVITIES	<p><b>Semiautonomous Seminar Co-Organizer</b> Jan 2020 - Dec 2021</p> <ul style="list-style-type: none"> <li>• Content: Weekly seminar on control theory, robotics, optimization, computer vision, and machine learning.</li> </ul>
PREPRINTS	<p><b>Chih-Yuan Chiu</b>, Chinmay Maheshwari, Pan-Yang Su, Shankar Sastry. “Dynamic Tolling in Arc-based Traffic Assignment Models,” submitted to <i>59th Annual Allerton Conference on Communication, Control, and Computing</i>, 2023. (<a href="https://arxiv.org/pdf/2307.05466.pdf">https://arxiv.org/pdf/2307.05466.pdf</a>)</p> <p><b>Chih-Yuan Chiu</b>, Shankar Sastry. “Parameter Estimation in Optimal Tolling for Traffic Networks Under the Markovian Traffic Equilibrium,” submitted to <i>59th Annual Allerton Conference on Communication, Control, and Computing</i>, 2023. (<a href="https://drive.google.com/file/d/1LM7BwxI4nt0py8J8TFyOyLXNHIBi4kL7/view?usp=sharing">https://drive.google.com/file/d/1LM7BwxI4nt0py8J8TFyOyLXNHIBi4kL7/view?usp=sharing</a>)</p> <p><b>Chih-Yuan Chiu</b>, Chinmay Maheshwari, Pan-Yang Su, Shankar Sastry. “Arc-based Traffic Assignment: Equilibrium Characterization and Learning,” accepted at <i>IEEE Conference on Decision and Control (CDC)</i>, 2023. (<a href="https://arxiv.org/pdf/2304.04705.pdf">https://arxiv.org/pdf/2304.04705.pdf</a>)</p> <p>Jingqi Li, <b>Chih-Yuan Chiu</b>, Lasse Peters, Fernando Palafox, Mustafa Karabag, Javier Alonso-Mora, Somayeh Sojoudi, Claire Tomlin, David Fridovich-Keil. “Scenario-Game ADMM: A Parallelized Scenario-Based Solver for Stochastic Noncooperative Games,” submitted to <i>IEEE Conference on Decision and Control (CDC)</i>, 2023. (<a href="https://arxiv.org/pdf/2304.01945.pdf">https://arxiv.org/pdf/2304.01945.pdf</a>)</p> <p>Lasse Peters, Andrea Bajcsy, <b>Chih-Yuan Chiu</b>, David Fridovich-Keil, Forrest Laine, Laura Ferranti, Javier Alonso-Mora. “Contingency Games for Multi-Agent Interaction,” (<a href="https://arxiv.org/pdf/2304.05483.pdf">https://arxiv.org/pdf/2304.05483.pdf</a>)</p> <p><b>Chih-Yuan Chiu</b>, Kshitij Kulkarni, Shankar Sastry. “A Novel Statistical Independence Test for Dynamic Causal Discovery with Rare Events,” submitted to <i>IEEE Conference on Decision and Control (CDC)</i>, 2023. (<a href="https://arxiv.org/pdf/2211.16596.pdf">https://arxiv.org/pdf/2211.16596.pdf</a>)</p>
CONFERENCE PUBLICATIONS	<p><b>Chih-Yuan Chiu</b>. “SLAM Backends with Objects in Motion: A Unifying Framework and Tutorial,” <i>American Control Conference (ACC)</i>, 2023. (<a href="https://arxiv.org/pdf/2207.05043.pdf">https://arxiv.org/pdf/2207.05043.pdf</a>).</p> <p><b>Chih-Yuan Chiu</b>, David Fridovich-Keil. “GTP-SLAM: Game-Theoretic Priors for Simultaneous Localization and Mapping in Multi-Agent Scenarios,” <i>IEEE Conference on Decision and Control (CDC)</i>, 2022. (<a href="https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=9992656">https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=9992656</a>).</p> <p><b>Chih-Yuan Chiu*</b>, Amay Saxena*, Joseph Menke, Ritika Shrivastava, Shankar Sastry. “Simultaneous Localization and Mapping: Through the Lens of Nonlinear Optimization,” <i>IEEE International Conference on Intelligent Robots and Systems (IROS)</i>, 2022. (*: Equal contribution.) (<a href="https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=9793570">https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=9793570</a>).</p> <p><b>Chih-Yuan Chiu*</b>, Chinmay Maheshwari*, Eric Mazumdar, Shankar Sastry and Lillian J. Ratliff. “Zeroth-Order Methods for Convex-Concave Minmax Problems: Applications to Decision-Dependent Risk Minimization”, <i>25th International Conference on Artificial Intelligence and Statistics (AISTATS)</i>, 2022. (*: Equal contribution.) (<a href="https://proceedings.mlr.press/v151/maheshwari22a/maheshwari22a.pdf">https://proceedings.mlr.press/v151/maheshwari22a/maheshwari22a.pdf</a>).</p> <p>Rahul Arya, <b>Chih-Yuan Chiu</b>, and Gireeja Ranade. “Stabilizability of Vector Systems with Uniform Actuation Unpredictability”, <i>IEEE International Symposium on Information Theory (ISIT)</i>, 2021. (<a href="https://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&amp;arnumber=9518286">https://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&amp;arnumber=9518286</a>).</p>

Jingqi Li, **Chih-Yuan Chiu**, Lasse Peters, Somayeh Sojoudi, Claire Tomlin, David Fridovich-Keil. “Cost Inference for Feedback Dynamic Games from Noisy Partial State Observations and Incomplete Trajectories,” *International Conference on Autonomous Agents and Multiagent Systems*, 2023. (<https://arxiv.org/pdf/2301.01398.pdf>).

**Chih-Yuan Chiu**<sup>\*</sup>, David Fridovich-Keil<sup>\*</sup>, and Claire Tomlin. “Encoding Defensive Driving as a Dynamic Nash Game,” *IEEE International Conference on Robotics and Automation (ICRA)*, 2020. (<sup>\*</sup>: Equal contribution.) (<https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=9560788>)

Forrest Laine, David Fridovich-Keil, **Chih-Yuan Chiu**, and Claire Tomlin. “Multi-Hypothesis Interactions in Game-Theoretic Motion Planning,” *IEEE International Conference on Robotics and Automation (ICRA)*, 2020. (<https://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=9561695>).

Forrest Laine, **Chih-Yuan Chiu**, Claire Tomlin, “Eyes-Closed Safety Kernels: Safety for Autonomous Systems Under Loss of Observability”, *Robotics: Science and Systems (RSS)*, 2020. (<https://www.roboticsproceedings.org/rss16/p096.pdf>).

JOURNAL  
PUBLICATIONS

Forrest Laine, David Fridovich-Keil, **Chih-Yuan Chiu**, and Claire Tomlin. “The Computation of Approximate Generalized Feedback Nash Equilibria”, *SIAM Journal on Optimization*. (<https://epubs.siam.org/doi/epdf/10.1137/21M142530X>).

WORKSHOP  
PUBLICATIONS

Druv Pai, Michael Psenka, **Chih-Yuan Chiu**, Manxi Wu, Edgar Dobriban, Yi Ma. “Pursuit of a Discriminative Representation for Multiple Subspaces via Sequential Games”, *Third Workshop on Seeking Low-Dimensionality in Deep Neural Networks*, 2023 (<https://arxiv.org/pdf/2206.09120.pdf>).

THESES

(*Master’s Thesis*) **Chih-Yuan Chiu**. “Simultaneous Localization and Mapping: A Rapprochement of Filtering and Optimization-Based Approaches,” 2021. (<https://www2.eecs.berkeley.edu/Pubs/TechRpts/2021/EECS-2021-76.pdf>).

REFERENCES

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